# SPECTRAL CRITERIA OF ABSTRACT FUNCTIONS; INTEGRAL AND DIFFERENCE PROBLEMS

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ABSTRACT. Let  $X$  be a complex Banach space and let  $M$  be a closed subspace of  $L^{\infty}(J,X)$ , where  $J \in \{R, R^+\}$ . We answer the following question: Under what conditions  $\phi_s - \phi \in M$   $\forall s \in J$  implies that  $\phi \in M$ . Some conditions will be imposed on  $M$  to obtain the main result concerning the indefinite integral. These conditions guarantee the following implication : F ∈  $E(J,X) \Longrightarrow F \in M$ , where F is the integral  $\int_0^t f(s) ds$  of  $f \in M \cap C_{ub}(J,X)$ . Also, we generalize Loomis' Theorem for almost periodic functions [19, Theorem 5, to a more general class of functions  $M\subseteq L^{\infty}(\mathbf{R},X)$  containing  $AP(\mathbf{R},X)$ . The main result of Part IV is: If  $\phi$  is uniformly continuous, bounded, such that the M-spectrum  $\sigma_M(\phi)$  of  $\phi$  is at most countable and, for every  $\lambda \in \sigma_M(\phi)$ , the function  $e^{-i\lambda t}\phi(t)$  is ergodic, then  $\phi \in M$ .

#### 1. INTRODUCTION

A continuous scalar function f on  $\bf{R}$  is called almost periodic (a.p) if the set of all translates  $\{f_w : w \in \mathbf{R}\}\$ is relatively compact (r.c) in  $C_b(\mathbf{R})$  ( $C_b(\mathbf{R})$ ) is the space of all scalar continuous bounded functions). Bohl and Bohr [8] proved that if f is a scalar almost periodic on  $\mathbf{R}$ , then  $F(t) = \int_0^t$ 0  $f(s) ds$  is a.p iff F is bounded (see also [22]). The almost periodicity of a function with values in a Banach space is defined similarly. M. I. Kadets [18] generalized this theorem and proved that: if  $f$  is an a.p from **R** to X which does not contain  $c_0$ , then F is a.p iff F is bounded. Here,  $c_0$  is the space of all numerical sequences tending to 0. Thereafter, he proved this theorem for arbitrary Banach spaces  $X$  when the range of F is weakly relatively compact (w.r.c) in X (see [19]). Instead of the above mentioned integral problem B. Basit [2] considered the difference problem and proved the following result: Suppose that  $f \in C_{ub}(G, X)$  such that  $f_s - f$  is a.p  $\forall s \in G$ . If either

(i) X does not contain a subspace isomorphic to  $c_0$ ,

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or

(ii)  $f(G)$  is w.r.c in X,

then  $f$  is a.p.

The case  $X = \mathbf{R}$  is proved by R. Doss [12]. See also F. Galvin, G. Muraz and P. Szeptycki [15] for a general group (nonabelian) and C. Datry and G. Muraz [11] for G-modules. See also E. Emmam [14] for almost automorphic functions. Here G is a group and  $f_s(t) = f(ts)$ . Mary L. Boas and R. P. Boas [15] proved that if f is bounded and  $f_s - f$  is continuous for every  $s \in \mathbf{R}$ , then f is continuous. This result is generalized by F. Galvin, G. Muraz and P. Szeptycki [15] and C. Datry and G. Muraz [11], for the uniformly continuous functions defined on a group with values in a Banach space. Levitan [20] proved the almost periodicity of the integral  $F$ ,

provided that F is bounded and  $\lim_{T \to \infty} (1/2T)$  $\frac{T}{c}$  $-T$  $F(t+s)$  ds exists uniformly

on R. Basit [4] extended Levitan' s result to recurrent functions. C. Datry and G. Muraz [11] extended the result of Levitan to Banach G-modules.

Throughout this paper, X is a complex Banach space with the norm  $\| \cdot \|$ and  $J \in \{R, R^+\}$ . We denote by  $L^{\infty}(J, X)$  the Banach space of all essentially bounded measurable functions with the norm  $||f||_{\infty} = ess \sup ||f(t)||$ .  $t\in J$ 

A function  $f$  is called measurable if there exists a sequence of simple functions  $\{f_n\}$  such that  $f_n \to f$  a.e with respect to the Lebesgue measure m. By a simple function it is meant a function of the form  $\sum_{n=1}^{\infty}$  $\sum_{i=1} x_i \chi_{A_i}, x_i \in X$ and  $\chi_{A_i}$  is the characteristic function of the Lebesgue measurable set  $A_i$ with finite measure. Finally, M denotes a closed subspace of  $L^{\infty}(J, X)$ .

In the sequel, we impose on  $M$  at least one of the following two conditions:

(P1) M is invariant under translations, i.e.  $\forall f \in M \ \forall s \in J \ (f_s \in M),$ where  $f_s(t) = f(t+s)$ .

(P2) M contains the constant functions.

In Section 2, we study examples of closed subspaces of  $L^{\infty}(\mathbf{R}, X)$  which satisfy one or both of the conditions (P1-P2).

The third section is devoted to extend the previous results of the integral problem or the difference problem to the general space  $M$ , i.e. what are the conditions that insure the following implication

$$
f \in M \bigcap C_{ub}(J, X) \Longrightarrow F(t) = \int_{0}^{t} f(s) ds \in M
$$

or

$$
\phi_s - \phi \in M \quad \forall s \in J \Longrightarrow \phi \in M.
$$

When  $f \in M = AAP(\mathbf{R}^+, X)$ , W. M. Ruess and W. H. Summers [28] proved that if  $f \in AAP(\mathbf{R}^+, X)$ , then

$$
F(t) = \int_{0}^{t} f(s) ds \in AAP(\mathbf{R}^{+}, X) \quad \text{iff } F \in W(\mathbf{R}^{+}, X).
$$

In this section, the notion of ergodic function in [13], [11] plays an essential role. A function  $\phi \in L^{\infty}(J, X)$  is called ergodic if there exists  $x \in X$  such that

$$
\lim_{T \to \infty} \|(1/T)\int_{0}^{T} (\phi_s(t) - x) ds\|_{\infty} = 0.
$$

We denote by  $E(J, X)$  the space of all ergodic functions. We prove that if  $\phi$  (resp. F) of the difference (resp. integral) problem is ergodic, then  $\phi \in M$  (resp.  $F \in M$ ).

In Section 4 M denotes a Banach subspace of  $L^{\infty}(\mathbf{R},X)$  which satisfies one or more of the conditions (P1-P3), where (P1-P2) are stated above and condition (P3) is:

(P3) M is invariant under multiplication by characters, i.e.  $\forall f \in M$   $\forall \lambda \in$  $\mathbf{R} \; (\breve{\lambda} \; f \in M), \text{ where } \breve{\lambda}(t) = e^{i \lambda t}.$ 

In Subsection 4.1 the M-spectrum of a function  $u \in L^{\infty}(\mathbf{R}, X)$  will be defined by

$$
\sigma_M(u) = Z(I_M(u)) = \{ \alpha \in \mathbf{R} : \hat{f}(\alpha) = 0 \,\,\forall f \in I_M(u) \},
$$

where  $\hat{f}(\alpha) =$  | R  $f(t)e^{-i\alpha t} dt$ , and  $I_M(u)$  is the ideal of all  $f \in L^1(\mathbf{R})$  such

that  $f * u \in M$ . In the case  $M = \{0\}$ ,  $\sigma_M(u)$  is the well-known classical Beurling spectrum. Some properties of the M-spectrum, which we need in proving our results, will be shown.

When  $M = AP(\mathbf{R}, \mathbf{C})$ , L. H. Loomis [21] proved that if  $u \in C_{ub}(\mathbf{R}, \mathbf{C})$  and  $\sigma_{AP(R)}(u)$  (the set of all non-almost periodicity of u) is at most countable, then  $u$  is a.p. B. Basit generalized this theorem in [5] to a class of bounded uniformly continuous vector-valued functions defined on  $\bf{R}$  with certain properties satisfied by many known classes.

In Subsection 4.2, we extend these results to a general closed subspace M of  $L^{\infty}(\mathbf{R}, X)$ . In this section, assuming that M satisfies (P1-P3), we prove that if  $\phi$  is uniformly continuous, bounded, such that  $\sigma_M(\phi)$  is at most countable, and for every  $\lambda \in \sigma_M(\phi)$  the function  $\left(-\lambda\right)\phi$  is ergodic, then  $\phi \in M$ . This theorem plays an essential role in proving the existence of solutions in some classes  $M \subseteq L^{\infty}(\mathbf{R}, X)$  for abstract functional equations defined on  $\bf{R}$  (see A. Hamza [17]).

Also, we prove the following result : Assume that  $\phi$  is uniformly continuous, bounded, such that  $\phi_s - \phi \in M \ \forall s \in \mathbf{R}$ . If  $0 \notin \sigma_M(\phi)$ , then  $\phi \in M$ .

As a direct consequence, we obtain a result concerning the indefinite As a direct consequence, we obtain a result concerning the indefinite<br>integral  $F(t) = \int_0^t f(s) ds$ , where  $f \in M \bigcap C_{ub}(\mathbf{R}, X)$ :  $0 \notin \sigma_M(F)$  implies  $F \in M$ .

### 2. Preliminaries and examples

In this section, for the convenience of the reader, we recall some definitions and examples of closed subspaces M satisfying  $(P1)$  or  $(P2)$  or  $(P1)$ and (P2) above. Consider the following closed subspaces of  $L^{\infty}(J, X)$ . (1)  $C_b(J, X) = \{f : J \to X : f \text{ is continuous and bounded}\}.$ (2)  $C_{ub}(J, X) = \{f : J \to X : f \text{ is uniformly continuous and bounded}\}.$ (3)  $AP(\mathbf{R}, X)$ -the Banach space of all almost periodic (a.p) functions. A function  $f \in C_b(\mathbf{R}, X)$  is called a.p if for every  $\varepsilon > 0$  the set

$$
E_{\varepsilon}(f) = \{ \tau \in \mathbf{R} : \sup_{t \in \mathbf{R}} ||f(t + \tau) - f(t)|| < \varepsilon \}
$$

is relatively dense (r.d) in **R**. A subset  $B \subseteq \mathbf{R}$  is said to be r.d if there exists  $\ell > 0$  such that  $\forall a \in \mathbf{R}$   $(a, a + \ell) \cap B \neq \emptyset$ . A function f is a.p iff  $H(f) = \{f_{\omega} : \omega \in \mathbf{R}\}\$ is relatively compact (r.c) in  $C_b(\mathbf{R}, X)$ , (see [1, 9, 20]).

(4)  $AP(\mathbf{R}^+, X) = AP(\mathbf{R}, X)|_{\mathbf{R}^+}$ , where  $AP(\mathbf{R}, X)|_{\mathbf{R}^+}$  is the restriction of the a.p functions on  $\mathbb{R}^+$ .

$$
(5) C_0(\mathbf{R}, X) = \{ f \in C_b(\mathbf{R}, X) : \lim_{|t| \to \infty} ||f(t)|| = 0 \}.
$$

(6) 
$$
C_0(\mathbf{R}^+, X) = \{ f \in C_b(\mathbf{R}^+, X) : \lim_{t \to \infty} ||f(t)|| = 0 \}.
$$

(7) 
$$
L_0^{\infty}(J, X) = \{ f \in L^{\infty}(J, X) : \lim_{|t| \to \infty} ||f(t)|| = 0 \}.
$$

(8)  $AAP(J, X) = AP(J, X) + C_0(J, X) = \{p+q : p \in AP(J, X), q \in$  $C_0(J, X)$ -the Banach space of all asymptotically almost periodic (a.a.p) functions from J to X. We notice that the decomposition  $p + q$ , where  $p \in AP(J, X)$  and  $q \in C_0(J, X)$ , is unique. Indeed, if  $p \in AP(J, X)$  then  $||p||_{\infty} = \limsup ||p(t)||$  (see [31]). So, if  $p \in AP(J, X) \cap C_0(J, X)$ , then  $t\rightarrow\infty$ 

 $p = 0$ . A function  $f \in AAP(\mathbf{R}^+, X)$  iff  $H(f) = \{f_\omega : \omega \in \mathbf{R}^+\}$  is r.c in  $C_b(\mathbf{R}^+, X)$  (see [25, 26]).

(9)  $S - AAP(J, X) = AP(J, X) + L_0^{\infty}(J, X)$ -the Banach space of all a.a.p in the sense of Staffans [31]. Also the decomposition  $p + q$ , where  $p \in$  $AP(J, X)$  and  $q \in L_0^{\infty}(J, X)$  is unique.

(10)  $AA(\mathbf{R}, X)$ -the Banach space of all almost automorphic (a.a) functions from **R** to X. A function  $f \in C_b(\mathbf{R}, X)$  is called a.a if for each sequence  ${a'_i}$  ${n \choose n} \subset \mathbf{R}$ , there exists a subsequence  $\{a_n\}$  such that

(i)  $\lim_{n\to\infty} f(t + a_n) = g(t), t \in \mathbb{R}$ , where g is a continuous function.

(ii)  $\lim_{n \to \infty} g(t - a_n) = f(t), t \in \mathbf{R}.$ 

It is well-known that an a.a function is uniformly continuous and its range is totally bounded. A uniformly continuous function with totally bounded range is a.a iff  $\forall \varepsilon > 0 \ \forall r > 0$  the set

$$
E_{\varepsilon,r}(f) = \{ \tau : \sup_{|t| \le r} ||f(t + \tau) - f(t)|| < \varepsilon \}
$$

is r.d in  $\mathbf{R}$ , (see [3, 10]). (11)  $AA(\mathbf{R}^+, X) = AA(\mathbf{R}, X)|_{\mathbf{R}^+}.$ 

**Lemma 2.1.** If  $f \in AA(J,X)$ , then  $||f||_{\infty} = \limsup_{t \to \infty}$  $||f(t)||.$ 

Proof. We have

(1) 
$$
||f||_{\infty} \geq \limsup_{t \to \infty} ||f(t)||.
$$

Let  $\varepsilon > 0$ , there exists  $x_{\varepsilon} \in J$  such that  $||f||_{\infty} \leq ||f(x_{\varepsilon})|| + \varepsilon$ . Since  $E_{\varepsilon,r}(f)$  is r.d, where  $r = |x_{\varepsilon}| + 1$ , there exists a sequence  $\{\tau_n\} \subset E_{\varepsilon,r}(f)$ such that  $\tau_n \to \infty$ . We have  $|| f(x_\varepsilon) || \le || f(x_\varepsilon + \tau_n) || + \varepsilon \ \forall n$ , whence  $|| f(x_\varepsilon) || \le \limsup ||f(t)|| + \varepsilon$ . Hence  $t\rightarrow\infty$ 

$$
||f||_{\infty} \le \limsup_{t \to \infty} ||f(t)|| + 2\varepsilon \quad \forall \varepsilon > 0.
$$

Therefore,

(2) 
$$
||f||_{\infty} \leq \limsup_{t \to \infty} ||f(t)||.
$$

We get from (1) and (2), that  $||f||_{\infty} = \limsup ||f(t)||$ .  $t\rightarrow\infty$ 

(12)  $AAA(J, X) = AA(J, X) + C_0(J, X)$ -the Banach space of all asymptotically almost automorphic functions (a.a.a). We have by the previous lemma that  $AA(J, X) \bigcap C_0(J, X) = \{0\}.$ 

(13)  $S - AAA(J, X) = AA(J, X) + L_0^{\infty}(J, X)$ -the Banach space of all a.a.a in the sense of Staffans. Also,  $AA(J, X) \bigcap L_0^{\infty}(J, X) = \{0\}.$ 

(14)  $W(J, X)$  the Banach space of all weakly almost periodic functions in the sense of Eberlien (w.a.p-E). A function  $f \in C_b(J, X)$  is called w.a.p-E if  $\{f_\omega : \omega \in J\}$  is w.r.c in  $C_b(J, X)$ . A function f is w.a.p-E iff f satisfies the double limit property, i.e.  $\forall \{\omega_n\} \subseteq J \quad \forall \{t_n\} \subseteq J \quad \forall \{x_n^*\} \subseteq X^*$  such that  $||x_n^*|| \leq 1$  we have

$$
\lim_{n \to \infty} \lim_{m \to \infty} x_n^*(f_{\omega_m}(t_n)) = \lim_{m \to \infty} \lim_{n \to \infty} x_n^*(f_{\omega_m}(t_n))
$$

whenever both of the limits exist, see [23].

(15)  $E(J, X)$ -the Banach space of all ergodic functions. A function  $\phi \in$  $L^{\infty}(J, X)$  is called ergodic if there exists  $x \in X$  such that

$$
\lim_{T \to \infty} \|1/T \int_0^T (\phi_s(t) - x) ds\|_{\infty} = 0.
$$

(16)  $TE(J, X) = \{ \phi \in L^{\infty}(J, X) : e^{i\lambda t} \phi(t) \in E(J, X) \ \forall \lambda \in \mathbf{R} \}.$ 

(17)  $E_0(J, X) = \{ \phi \in E(J, X) : \lim_{T \to \infty} ||1/T \int_{0}^{T}$ 0  $\phi_s ds \rVert_{\infty} = 0.$ 

Lemma 2.2. The spaces in Examples (1-17) are closed subspaces of  $L^{\infty}(J, X)$  satisfying (P1) and the spaces in Examples (1-4), (8-16) satisfy  $(P2)$ . The spaces in Examples  $(5-7)$  and  $(17)$  don't satisfy  $(P2)$ .

Lemma 2.3.  $AP(J, X) \subset AAP(J, X) \subset W(J, X) \subset TE(J, X).$ 

*Proof.* We can check that  $C_0(J, X) \subset W(J, X)$ . Indeed, suppose that  $f \in C_0(J, X)$ . Let  $\{t_n\}$  and  $\{\omega_n\}$  be two sequences in J. Let  $\{x_n^*\}$  be a sequence in  $X^*$  such that  $||x_n^*|| \leq 1$  and both of the following iterated limits

$$
\lim_{m \to \infty} \lim_{n \to \infty} x_n^*(f_{\omega_m}(t_n))
$$

and

$$
\lim_{n \to \infty} \lim_{m \to \infty} x_n^*(f_{\omega_m}(t_n))
$$

exist. We have the following cases:

(i) both of  $\{t_n\}$  and  $\{\omega_n\}$  are unbounded. In this case we can suppose without loss of generality that  $t_n \to \infty$  and  $\omega_n \to \infty$ .

(ii) one of the two sequences, say  $\{t_n\}$ , is unbounded and the other is bounded. In this case we can suppose that  $t_n \to \infty$  and  $\omega_n \to a$  for some  $a \in J$ .

(iii) both of the two sequences are bounded. We can assume in this case that  $t_n \to a$  and  $\omega_n \to b$  for some a and b in J.

In case (i) both of the iterated limits equal zero. In case (ii), the first iterated limit equals zero. The second iterated limit equals

$$
\lim_{n \to \infty} x_n^*(f_a(t_n)) = 0.
$$

In case (iii) we use the uniform continuity of  $f$  to conclude that the two iterated limits are equal. The fact that  $W(J, X) \subset TE(J, X)$  is a result of [13]. To show that both of  $AP(J, X)$ ,  $AAP(J, X)$  and  $W(J, X)$  are subsets of  $C_{ub}(J, X)$ , see [20, 23, 30].

#### 3.The difference and the integral problem

As before we assume that M is a closed subspace of  $L^{\infty}(J, X)$ . In this section we study the difference problem, viz we answer the following question: Under what conditions, does  $\phi_s - \phi \in M$   $\forall s \in J$  imply that  $\phi \in M$ . As a direct consequence we get a result concerning the indefinite integral problem (see [2, 8, 14, 18, 20, 22, 28]). L. H. Loomis [21] imposed the condition  $\phi \in C_{ub}(\mathbf{R}, \mathbf{C})$  to get  $\phi \in AP(\mathbf{R}, \mathbf{C})$ . When  $M = AP(\mathbf{R}, X)$ , B. Basit [2] supposed the same condition  $\phi \in C_{ub}(\mathbf{R}, X)$ to get  $\phi \in AP(\mathbf{R}, X)$ , provided that X does not contain  $c_0$  or the range of  $\phi$  is w.r.c in X. In fact this condition is not necessary because  $\phi$  will be uniformly continuous and bounded according to Theorem 3.0 stated below. In case  $M = C_b(\mathbf{R}, \mathbf{R})$ , Mary L. Boas and R. P. Boas [15] proved that: If  $\phi : \mathbf{R} \to \mathbf{R}$  is bounded on a set of positive measure and  $\phi_s - \phi$ is continuous for every  $s \in \mathbf{R}$ , then  $\phi$  is continuous. We can see some generalizations of this result in [11] and [15].

According to a general result of C. Datry and G. Muraz [11], we have the following theorem:

**Theorem 3.0.** A bounded function  $\phi : \mathbf{R} \to X$  is uniformly continuous iff  $\phi_s - \phi$  is uniformly continuous for every  $s \in \mathbf{R}$ .

**Lemma 3.1.** Let  $\phi \in C_{ub}(J,X)$ . If  $\phi_s - \phi \in M$   $\forall s \in J$ , then  $\int_J (\phi_s \phi$ )  $d\mu(s) \in M$  for every bounded Borel measure on J.

*Proof.* The function  $g: J \to M$  defined by  $g(s) = \phi_s - \phi$  is bounded and continuous, since  $\phi \in C_{ub}(J, X)$ . Suppose that  $\mu$  is a bounded Borel measure. Hence, g is measurable with respect to  $\mu$  (see Pettis' Theorem [32, p. 131]). We apply Bochner's Theorem [32, p. 133] to get  $\int_J g(s) d\mu(s) \in M$ p. 151]). We apply Bochner<br>i.e.  $\int_J (\phi_s - \phi) d\mu(s) \in M$ .

**Lemma 3.2.** Let  $\phi \in L^{\infty}(J,X)$  be such that  $\phi_s - \phi \in M \ \forall s \in J$ . **Lemma 3.2.** Let  $\varphi \in L^{\infty}(J, X)$  be such that  $\varphi_s - \varphi \in M$   $\forall s \in J$ .<br>If there exists a bounded Borel measure  $\mu$  such that  $\int_J d\mu(s) \neq 0$  and  $\int_J \phi_s d\mu(s) = 0$ , then  $\phi \in M$ .

**Theorem 3.3.** Let M satisfy (P2). Suppose that  $\phi \in C_{ub}(J, X)$  $\overline{a}$  $E(J, X)$ . If  $\forall s \in J$   $\phi_s - \phi \in M$ , then  $\phi \in M$ .

*Proof.* There exists  $x \in X$  such that  $\phi - x \in E_0(J, X)$ . By condition (P2) M contains the constant function  $x(t) = x, t \in J$ . We apply Lemma 3.1 M contains the constant function  $x(t) = x$ ,  $t \in J$ . We apply Lemma 3.1<br>to get  $\int_J (\phi_s - \phi) d\mu_T(s) \in M$ , where  $d\mu_T(s) = (1/T) \chi_{[0,T]}(s) ds$ ,  $T > 0$ . Hence,  $(1/T)$  $\frac{T}{c}$ 0  $(\phi_s - \phi) ds \in M \quad \forall T > 0$ . Taking the limit as  $T \to \infty$ , we get  $\phi \in M$  (*M* is closed).

**Theorem 3.4.** Let M satisfy (P1-P2). Suppose that  $f \in M$  $\overline{a}$  $C_{ub}(J, X)$ . **If the function** F defined by  $F(t) = \int_0^t f(s) ds$  belongs to  $E(J, X)$ , then  $F \in M$ .

*Proof.* We have  $(F_s - F)(t) = \int_s^s$ 0  $f_u(t) du$ ,  $s \in J$ ,  $t \in J$ . Fix s and let I be the interval with end points 0 and s. The function  $g: I \to M$  defined be the interval with end points 0 and s. The function  $g: I \to M$  defined<br>by  $g(u) = f_u$  is continuous. Since  $\int_J ||g(u)||_{\infty} ds \leq |s| ||f||_{\infty} < \infty$ , then  $\frac{s}{c}$ 0  $f_u du \in M$ . Hence  $F_s - F \in M \,\forall s \in J$ . By Theorem 3.3, we get  $F \in M$ .

**Corollary 3.5.** Let  $f \in C_b(J, X)$  and  $F(t) = \int_a^t f(t) dt$ 0  $f(s)$  ds. Then the following statements are true.

- (1) If  $f \in AP(J, X)$  and  $F \in E(J, X)$ , then  $F \in AP(J, X)$ .
- (2) If  $f \in AAP(J, X)$  and  $F \in E(J, X)$ , then  $F \in AAP(J, X)$ .
- (3) If  $f \in AAP(J, X)$  and  $F \in W(J, X)$ , then  $F \in AAP(J, X)$ .
- (4) If  $f \in AA(J, X)$  and  $F \in E(J, X)$ , then  $F \in AA(J, X)$ .
- (5) If  $f \in AAA(J, X)$  and  $F \in E(J, X)$ , then  $F \in AAA(J, X)$ .

*Proof.* The statements  $(1)$ ,  $(2)$ ,  $(4)$  and  $(5)$  are true, since all of the following spaces  $AP(J, X)$ ,  $AAP(J, X)$ ,  $AA(J, X)$  and  $AAA(J, X)$  satisfy (P1-P2). The statement (3) is true, since  $W(J, X) \subset TE(J, X)$ .

### 4. Spectral criteria of abstract functions

In this section M denotes a closed subspace of  $L^{\infty}(\mathbf{R},X)$  which satisfies one or more conditions on  $M$  from the following list:

- (P1) M is invariant under translations, i.e.  $\forall f \in M \ \forall s \in \mathbf{R} \ (f_s \in M),$ where  $f_s(t) = f(t+s)$ .
- (P2) M contains the constant functions.
- (P3) M is invariant under multiplication by characters, i.e.  $\forall f \in M$   $\forall \lambda \in$  $\mathbf{R}(\breve{\lambda} f \in M)$ , where  $\breve{\lambda}(t) = e^{i\lambda t}$ .

We consider the closed subspaces of  $L^{\infty}(\mathbf{R}, X)$  which are given in Section 2. We can check that all of them satisfy (P3) except the spaces in Examples (15) and (17). We can prove that  $W(\mathbf{R}, X)$  satisfies (P3), by showing that for every  $f \in W(\mathbf{R}, X)$  and for every  $\lambda \in \mathbf{R}$  the function  $\check{\lambda}$  f satisfies the double limit property, where  $\check{\lambda}(t) = e^{i\lambda t}$ .

## 4.1. The M-spectrum of functions in  $L^{\infty}(\mathbf{R},X)$

**Definition 4.1.1.** For a function  $u \in L^{\infty}(\mathbf{R}, X)$  and  $f \in L^{1}(\mathbf{R})$  denote by

$$
(f * u)(t) = \int_{\mathbf{R}} f(t - s)u(s) ds, \qquad t \in \mathbf{R}.
$$

**Lemma 4.1.2** (see also [5]). If M is a closed subspace of  $L^{\infty}(\mathbf{R}, X)$ satisfying (P1), then

$$
\forall f \in L^1(\mathbf{R}) \,\,\forall u \in M \bigcap C_{ub}(\mathbf{R}, X) \,(f * u \in M)\,.
$$

*Proof.* Let  $f \in L^1(\mathbf{R})$  and  $u \in M$  $\overline{a}$  $C_{ub}(\mathbf{R}, X)$ . Define the function  $g: \mathbf{R} \to M$  by

$$
g(s) = u_{-s}.
$$

The function q is continuous and bounded, since  $u$  is uniformly continu-The function g is continuous and bounded, since u is uniformly continuous. Applying Bochner's Theorem [32, p. 133], we get  $\int_{\mathbf{R}} f(s) u_{-s} ds \in M$ , whence  $f * u \in M$ 

**Lemma 4.1.3.** If  $u \in L^{\infty}(\mathbf{R}, X)$ , then the following conditions are equivalent

- (i)  $u \in C_{ub}(\mathbf{R}, X)$ ,
- (ii)  $\lim_{t \to 0} ||u_t u||_{\infty} = 0,$

(iii) 
$$
\lim_{T \to 0} \|\rho_T * u - u\|_{\infty} = 0, \text{ where } \rho_T = \frac{1}{T} \chi_{[-T,0]}, T > 0. \text{ Here } \chi_{[-T,0]}
$$
  
is the characteristic function of the interval [-T,0].

This is a classical result in the theory of  $L^1(G)$ -modules. We can replace  $\{\rho_T\}$  by any bounded approximate of identity (see [11]).

**Definition 4.1.4** (see [6, 14, 5]). Suppose that M is a closed subspace of  $L^{\infty}(\mathbf{R},X)$  such that (P1) holds. Let  $u \in L^{\infty}(\mathbf{R},X)$ . We denote by

$$
I_M(u) = \{ f \in L^1(\mathbf{R}) : f * u \in M \}.
$$

The set  $I_M(u)$  is a closed ideal of  $L^1(\mathbf{R})$ .

We denote the M-spectrum  $\sigma_M(u)$  of  $u \in L^\infty(\mathbf{R}, X)$  by

$$
\sigma_M(u) = Z(I_M(u)) = \{ \alpha \in \mathbf{R} : \hat{f}(\alpha) = 0 \quad \forall f \in I_M(u) \},
$$

where  $\hat{f}(\alpha) = \int_{\mathbf{R}} f(t)e^{-i\alpha t} dt$ . The spectrum  $\sigma(u)$  is denoted by  $\sigma(u) =$ :  $\sigma_{\{0\}}(u)$ . It is clear that  $\sigma_M(u) \subseteq \sigma(u)$ .

**Lemma 4.1.5** (see also [14, 5]). Let  $u \in L^{\infty}(\mathbf{R}, X)$ . If M is a closed subspace of  $L^{\infty}(\mathbf{R},X)$  satisfying (P1), then the following hold:

- (1)  $\sigma_M(u) = \emptyset$  iff  $\forall f \in L^1(\mathbf{R})$   $f * u \in M$ .
- (2) If  $u \in C_{ub}(\mathbf{R}, X)$  then  $\sigma_M(u) = \emptyset$  iff  $u \in M$ .
- (3) If  $\sigma_M(u) = \{0\}$ , then  $f * (u_s u) \in M \ \forall f \in L^1(\mathbf{R}) \quad \forall s \in \mathbf{R}$ .
- (4) If  $u \in C_{ub}(\mathbf{R}, X)$ , then  $\sigma_M(u) = \{0\} \Longrightarrow u_s u \in M \ \forall s \in \mathbf{R}$ .
- (5)  $\sigma_M(f * u) \subseteq \text{supp } \hat{f} \bigcap \sigma_M(u) \ \forall f \in L^1(\mathbf{R}).$
- (6) If in addition M satisfies (P3), then

$$
\sigma_M(\breve{\gamma}u)=\sigma_M(u)+\gamma\,\,\forall \gamma\in{\bf R},
$$

where  $\breve{\gamma}(t) = e^{i\gamma t}$ .

*Proof.* (1) We have  $Z(I_M(u)) = \emptyset$  iff  $I_M(u) = L^1(\mathbf{R})$ . Hence  $\sigma_M(u) = \emptyset$ iff  $\forall f \in L^1(\mathbf{R})$   $f * u \in M$ .

(2) Let  $u \in C_{ub}(\mathbf{R}, X)$ . Suppose that  $\sigma_M(u) = \emptyset$ . Hence, by (1) we have  $f * u \in M \ \forall f \in L^1(\mathbf{R})$ . By Lemma 4.1.3  $\lim_{T \to 0} ||\rho_T * u - u||_{\infty} = 0$  whence  $u \in M$ . Conversely, suppose that  $u \in M$ . By Lemma 4.1.2, we get that  $f * u \in M \ \forall f \in L^1(\mathbf{R})$ , which in return implies that  $\sigma_M(u) = \emptyset$ .

(3) Suppose that  $a_M(u) = \{0\}$ , i.e.  $Z(I_M(u)) = \{0\}$ , where  $\{0\}$  is a set of spectral synthesis. We have  $I_M(u) = \{f \in L^1(\mathbf{R}) : \hat{f}(0) = 0\}$ . Hence,  $(f_s - f) * u \in M \ \forall s \in \mathbf{R} \ \forall f \in L^1(\mathbf{R})$ , whence  $f * (u_s - u) \in M \ \forall s \in \mathbf{R}$  $\forall f \in L^1(\mathbf{R}).$ 

(4) is a direct consequence of (3) and (2).

(5) Let  $f \in L^1(\mathbf{R})$ . Let  $\alpha \in \sigma_M(f * u)$ . To show that  $\alpha \in \sigma_M(u)$ , let

 $h \in L^1(\mathbf{R})$  be such that  $h * u \in M$ . Then  $h * (f * u) = f * (h * u) \in M$ . Therefore  $\hat{h}(\alpha) = 0$  and we get  $\alpha \in \sigma_M(u)$ .

Now we show that  $\alpha \in \text{supp } \hat{f}$ . Suppose on the contrary that  $\alpha \notin \text{supp } \hat{f}$ . Then there exists  $g \in L^1(\mathbf{R})$  such that  $\hat{g}(\alpha) \neq 0$  and  $\hat{g}(\text{supp }\hat{f}) = \{0\}.$ We have  $g * f = 0$  whence  $g * f * u = 0 \in M$ . Hence  $\hat{g}(\alpha) = 0$  which is a contradiction.

(6) We denote by  $g = \gamma_0 u, \gamma_0 \in \mathbf{R}$ . Let  $\gamma \in \sigma_M(g)$ . Let  $f \in L^1(\mathbf{R})$  be such that  $f * u \in M$ . A simple calculation shows that

$$
(\breve{\gamma_0}f)*g = \breve{\gamma_0}(f*u).
$$

Hence  $(\breve{\gamma_0} f) * g \in M$ , whence  $(\breve{\gamma_0} f) (\gamma) = 0$ , i.e.  $\hat{f}(\gamma - \gamma_0) = 0$  and we get  $\gamma - \gamma_0 \in \sigma_M(u)$ . Conversely, let  $\gamma \in \sigma_M(u)$  and  $f \in L^1(\mathbf{R})$  be such that  $f * g \in M$ . We have

$$
f * g = (\check{\gamma_0}) [((-\gamma_0) \check{f}) * u].
$$

Hence,  $((-\gamma_0) f) * u \in M$ , whence  $((-\gamma_0) f)(\gamma) = 0$ , i.e.  $\hat{f}(\gamma + \gamma_0) = 0$ and we get  $\gamma + \gamma_0 \in \sigma_M(q)$ .

#### 4.2. Spectral characterization of the classes M

A theorem of Loomis [21] states that: If  $\phi \in C_{ub}(\mathbf{R})$  and  $\sigma_{AP(\mathbf{R})}(\phi)$ is at most countable, then  $\phi \in AP(\mathbf{R})$ . In this section, we generalize this theorem to more general classes of functions  $M \subseteq L^{\infty}(\mathbf{R}, X)$  containing  $AP(\mathbf{R}, X)$ . We prove the following result: If  $\phi$  is uniformly continuous, bounded, such that the M-spectrum  $\sigma_M(\phi)$  of  $\phi$  is at most countable and, for every  $\lambda \in \sigma_M(\phi)$ , the function  $e^{-i\lambda t}\phi(t)$  is ergodic, then  $\phi \in M$ .

**Lemma 4.2.1.** If  $\lambda_0 \in \mathbb{R}$  is such that  $(-\lambda_0) \phi \in E(\mathbb{R}, X) \cap$  $C_{ub}(\mathbf{R}, X),$ then  $\lambda_0$  cannot be an isolated point of  $\sigma_M(\phi)$ .

*Proof.* Let  $\lambda_0 \in \mathbb{R}$  be such that  $(-\lambda_0) \phi \in E(\mathbb{R}, X) \cap$  $C_{ub}(\mathbf{R}, X)$ . Suppose on the contrary that  $\lambda_0$  is an isolated point of  $\sigma_M(\phi)$ . There exists a compact neighbourhood V of  $\lambda_0$  such that  $V \bigcap (\sigma_M(\phi) \setminus {\lambda_0}) = \emptyset$ . Choose  $f \in L^1(\mathbf{R})$  such that  $\hat{f}(\lambda_0) \neq 0$  and  $\hat{f}(\mathcal{C}V) = \{0\}$ . Here,  $\mathcal{C}V$  is the complement of V. Hence,  $\sigma_M(f * \phi) \subseteq \sigma_M(\phi) \cap \text{supp } \hat{f} \subseteq {\lambda_0},$  whence  $\sigma_M(f * \phi) = {\lambda_0}.$  By Lemma 4.1.5., we get

$$
[(-\lambda_0 \breve{)}(f * \phi)]_s - [(-\lambda_0 \breve{)}(f * \phi)] \in M \quad \forall s \in \mathbf{R}.
$$

Since  $(-\lambda_0)(f * \phi) = (-\lambda_0) \check{f} * (-\lambda_0) \check{\phi} \in E(\mathbf{R}, X) \cap$  $C_{ub}(\mathbf{R}, X)$ , then, by Theorem 3.3, we get  $(-\lambda_0)(f * \phi) \in M$ , whence  $f * \phi \in M$ . Hence,  $\hat{f}(\lambda_0) = 0$ , which is a contradiction.

**Theorem 4.2.2.** Let  $\phi \in C_{ub}(\mathbf{R}, X)$ . If  $\sigma_M(\phi)$  is at most countable such that the function  $(-\lambda) \phi \in E(\mathbf{R}, X)$  for every  $\lambda \in \sigma_M(\phi)$ , then  $\phi \in M$ .

*Proof.* Suppose that  $\phi \in C_{ub}(\mathbf{R}, X)$  satisfies the hypothesis of the theorem. We show that  $\sigma_M(\phi) = \emptyset$ . Suppose on the contrary that  $\sigma_M(\phi) \neq \emptyset$ . Then  $\sigma_M(\phi)$  (at most countable) has an isolated point  $\lambda_0$  [7]. Since  $(-\lambda_0)\phi \in$  $E(\mathbf{R}, X) \bigcap C_{ub}(\mathbf{R}, X)$ , then by Lemma 4.2.1, we get that  $\lambda_0$  is not an isolated point of  $\sigma_M(\phi)$  which is a contradiction.

**Corollary 4.2.3.** Let M be as in Theorem 4.2.2 and let  $\phi \in C_{ub}(\mathbf{R}, X)$  $\bigcap TE(\mathbf{R}, X)$ . If  $\sigma_M(\phi)$  is at most countable, then  $\phi \in M$ .

Proof. It is an immediate consequence of the previous theorem.

In the following theorem we impose a condition on  $\sigma_M(\phi)$  that insures the following implication:

$$
\phi_s - \phi \in M \,\,\forall s \in \mathbf{R} \Longrightarrow \phi \in M.
$$

**Theorem 4.2.4.** Assume that M is a closed subspace of  $L^{\infty}(\mathbf{R}, X)$ . Let  $\phi \in L^{\infty}(\mathbf{R}, X)$  be such that  $0 \notin \sigma_M(\phi)$ . If  $\phi_s - \phi \in M \cap C_{ub}(\mathbf{R}, X)$  $\forall s \in \mathbf{R}$ , then  $\phi \in M$ .

*Proof.* By Theorem 3.0,  $\phi \in C_{ub}(\mathbf{R}, X)$ . Since  $0 \notin \sigma_M(\phi)$ , there exists  $f \in L^1(\mathbf{R})$  such that  $f * \phi \in M$  and  $\hat{f}(0) = 1$ . By Lemma 3.1, we get  $f * \phi - \phi \in M$ , whence  $\phi \in M$ .

**Corollary 4.2.5.** Assume that M is a closed subspace of  $L^{\infty}(\mathbf{R}, X)$  satisfying (P1). Let  $f \in M$  $\bigcap C_{ub}({\bf R},X)$ . Define F by  $F(t) = \int_0^t$ 0  $f(s) ds$ . If  $0 \notin \sigma_M(F)$ , then  $F \in M$ .

*Proof.* We have  $(F_s - F)(t) = \int_s^s$ 0  $f_u(t) du, s \in \mathbf{R}, t \in \mathbf{R}$ . By the same argument as in Theorem 3.4, it follows that  $F_s - F \in M \ \forall s \in \mathbf{R}$ . By Theorem 4.2.4, we get  $F \in M$ .

In the applications of all these results given by A. Hamza in [17] for the solutions of functional equations or differential equations, the condition " $\phi$  is continuous" is not a restriction, because in general case, it is more than continuous.

To stay complete, we must report the Banach space  $BAUC(J, X)$  of all bounded asymptotically uniformly continuous functions from J to X (see [31]); sometimes such function is called *slowly oscillating* [24].  $\phi \in$  $BAUC(J, X)$  if  $\phi \in L^{\infty}(J, X)$  and lim  $\lim_{(t,x)\to(\infty,0)} |\phi_x(t) - \phi(t)| = 0.$ 

In fact, we have  $BAUC(J, X) = C_{ub}(J, X) + L_0^{\infty}(J, X)$ . This space verifies the properties (P1), (P2), (P3) and have some importance for the application in [17].

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