

## BAYESIAN ESTIMATION UNDER ESTIMATION CONSTRAINT

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ABSTRACT. We suppose that a constraint is imposed on the value of the estimator in Bayesian Estimation Theory and study the distribution of this estimator under various hypotheses, using the two main loss functions: the absolute value and the quadratic.

### 1. INTRODUCTION

In classical Bayesian Estimation Theory the prior distribution  $f(\theta)$  provides the first information on the parameter to be estimated. With the loss function considered,  $L(\theta, w)$ , the estimator is the value that would minimize the average loss or  $\int_{\mathfrak{R}} L(\theta, w) f(\theta) d\theta$ .

Considering the statistical model  $h(x|\theta)$ , let  $\vec{x}$  be the observations obtained on the model and  $f(\theta|\vec{x})$  the posterior distribution of  $\theta$ . The optimal estimation is now the value that would minimize the average posterior loss.

In the case of a quadratic loss (Pham-Gia and Tukkan [7]) that estimation is the posterior mean, with the corresponding average loss equal the posterior variance. For the absolute value loss function, the corresponding quantities are the posterior median and the posterior mean absolute deviation (Pham-Gia, Duong and Tukkan, [6]).

In this article we suppose that the estimator is subject to a certain constraint, as it is often in real applications, and cannot take the optimal value which is either the mean or the median. That constraint could be a fixed interval  $[a, b]$ , for example. Alternately, we can also suppose that the estimator itself is subject to a family of probability distributions, and will look for estimation optimality under this constraint. The behavior of the model under this non-optimal (in the classical sense) estimation will also be studied... We consider the two common loss functions  $L_i(\theta, w) = K_i |\theta - w|^i$ ; ( $i = 1, 2$ ) only since difficulties associated with cases  $i > 2$ , as presented in Bar-Lev et al. (see [1]), do not allow the deviation of the associated solutions.

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In Section 2 we will recall the main properties of the two dispersion functions that will play fundamental roles in the study of the above problem: the mean absolute deviation and the variance, both taken about an arbitrary point in  $\mathfrak{R}$  and considered as functions of this point. In Section 3 results on the optimal estimator, the posterior risk and the Bayes risk, are presented according to two hypothesis: the constraint is a fixed interval  $[a, b]$  within which the estimation must lie, and a finite set of distributions  $\{W_j\}$  from which to choose the best distribution of the estimator.

## 2. THE MEAN ABSOLUTE DEVIATION AND THE VARIANCE FUNCTIONS

Let  $\Theta$  be a random variable defined on  $\mathfrak{R}$ , with distribution  $F_\Theta(w)$  and finite mean  $\mu$ . We defined the absolute deviation function of  $\Theta$  at a point  $w \in \mathfrak{R}$ , also known as the dispersion function of  $\Theta$  at  $w$ , as  $\delta_\Theta(w) = E(|\Theta - w|)$ . According to [6], we have

$$(2.1) \quad \delta_\Theta(w) = \mu - w + 2[wF_\Theta(w) - \mu\phi(w)],$$

where  $\phi$  is the incomplete first moment of  $\Theta$ , defined by

$$\phi(w) = \mu^{-1} \int_{-\infty}^w t dF_\Theta(t).$$

On the other hand, Munoz-Perez and Sanchez-Gomez (see for details in [4]) have given the expression of the distribution  $F_\Theta(w)$  of  $\Theta$ , in terms of the derivative of  $\delta_\Theta(w)$  as follows

$$(2.2) \quad F_\Theta(w) = \frac{1}{2}[\delta'_\Theta(w) + 1],$$

which can also be obtained from (2.1).

It is worth pointing out that the formula (2.1) can be as follows (see for instance [12])

$$(2.3) \quad \begin{aligned} \delta_\Theta(w) &= w - \mu + 2 \int_{x \geq w} (x - w) dF_\Theta(x) \\ &= \mu - w + 2 \int_{x < w} (w - x) dF_\Theta(x). \end{aligned}$$

or, if  $X$  be a discrete random variable with distributions  $p_n = P(X = x_n)$ ,  $n \geq 0$ , then

$$\begin{aligned}
 \delta_{\Theta}(w) &= \sum_n |x_n - w| p_n \\
 &= w - \mu + 2 \sum_{n:x_n \geq w} (x_n - w) p_n \\
 (2.4) \qquad &= \mu - w + 2 \sum_{n:x_n < w} (w - x_n) p_n.
 \end{aligned}$$

The  $\delta_{\Theta}(w)$  is shown to have the following properties:

- a. It is continuously differentiable a.e. and convex on  $\mathfrak{R}$ ,
- b.  $\lim_{w \rightarrow +\infty} \delta'_{\Theta}(w) = 1$  and  $\lim_{w \rightarrow -\infty} \delta'_{\Theta}(w) = -1$ .
- c. It is the  $L^1$  distance (with respect to the Lebesgue measure on  $\mathfrak{R}$ ) between  $F_{\Theta}$  and  $F_w$ , where  $F_w$  is the distribution of the degenerate variable at the point  $w$ . We have

$$(2.5) \qquad \int_{\mathfrak{R}} |F_{\Theta}(x) - F_w(x)| dx = \delta_{\Theta}(w).$$

- d. The  $L^1$  norm (with respect to the Lebesgue measure) of the difference  $(\delta_{\Theta}(w) - \delta_{\Theta}(\mu))$  is the variance  $\sigma_{\Theta}^2$  of  $\Theta$ , where  $\delta_{\Theta}(\mu) = |\mu - w|$  is the dispersion function of the degenerate variable at  $E(\Theta) = \mu$ , i.e. we have

$$(2.6) \qquad \int_{\mathfrak{R}} |\delta_{\Theta}(w) - \delta_{\Theta}(\mu)| dw = \sigma_{\Theta}^2.$$

It is to be noticed that according to (2.6) some results related to upper bounds of the  $L^1$  distances of two dispersion functions have been established in [18].

When  $\mu$  and  $Md$  exist and are unique, the value of  $\delta_{\Theta}(w)$  at  $w = \mu$  and at  $w = Md$  play particular roles in Applied Statistics and Economics, being denoted respectively by  $\delta_1(\mu)$  and  $\delta_2(\Theta) = \delta_{\Theta}(Md)$ . Pham-Gia and Tukkan [7], used these measures in the study of income distributions associated with the beta distribution, while Gastwirth [2] studied the statistical properties of the standard measure of relative uniformity in tax assessments which is based on  $\delta_2(\Theta)$ .

Furthermore, Munoz-Perez and Sanchez-Gomez [5] have proved that  $\delta_X(w) - \mu_X \leq \delta_Y(w) - \mu_Y$  is equivalent to dilation ordering, by which  $X \leq^{\text{dil}} Y$  if  $E[\Phi(X - \mu_X)] \leq E[\Phi(Y - \mu_Y)]$ , for any convex function  $\Phi$ .

Some interesting results concerning the connection of the weak convergence of the random variables with the convergence of the dispersion functions have been investigated in [17]. The results obtained in [17] can be applied to some problems of theory of limit theorems for sum of independent random variables.

On the other hand, the variance of a random variable  $\Theta$ , with distribution  $F_\Theta(\theta)$ , about any point  $w$ , denoted  $V_\Theta(w)$  is defined as

$$(2.7) \quad V_\theta(w) = \int_{\mathfrak{R}} (\theta - w)^2 dF_\Theta(\theta) = \sigma_\Theta^2 + (w - \mu)^2,$$

where  $\sigma_\Theta^2$  is the variance of  $\Theta$  about its mean  $\mu$ . Although both  $\delta_\Theta$  and  $V_\Theta(w)$  are convex functions,  $V_\Theta(w)$  displays a symmetry about  $w = \mu$  whereas  $\delta_\Theta(w)$  is asymmetric, with minimum value of  $\delta_2(\Theta)$  at  $w = Md$ . For values  $k_1, k_2$  within some ranges, we then have 2 distinct values  $c_1, c_2$  and  $d_1, d_2$  such that

$$\delta_\Theta(c_1) = \delta_\Theta(c_2) = k_1$$

and

$$V_\Theta(d_1) = V_\Theta(d_2) = k_2.$$

### 3. ESTIMATION UNDER CONSTRAINT OF THE ESTIMATOR

**3.1.** Let us consider the simple case where the estimator of  $\theta$  belongs to an interval on  $\mathfrak{R}$ , say  $[a, b]$  and let  $L(\Theta, w)$  be the loss function. The posterior risk is then  $\int_{\mathfrak{R}} L(\Theta, w) f(\theta|\vec{x}) d\theta$  and let  $\theta_0$  be the value that would minimize that risk inside  $[a, b]$ , i.e.  $\lim_{w \in [a, b]} \int_{\mathfrak{R}} L(\Theta, w) f(\theta|\vec{x}) d\theta$  is attained for  $w = w_0$ .

We then take  $\hat{\Theta} = w_0$ . The posterior risk is  $\int_{\mathfrak{R}} L(\Theta, w_0) f(\theta|\vec{x}) d\theta$  and the Bayes risk is  $\int_{\mathfrak{R}} \Psi_n(x) dx = \int_{\mathfrak{R}} L(\Theta, w_0) f(\theta|\vec{x}) d\theta$ , where  $\Psi_n$  is the predictive distribution of  $x$ , based on  $\vec{x}$ , a vector of observations of size  $n$ .

Consider the following loss functions: the absolute value one of the form

$$L_1(\Theta, w) = K_1 |w - \theta|, \quad K_1 > 0,$$

and the quadratic one of the form

$$L_2(\Theta, w) = K_2 |w - \theta|^2, \quad K_2 > 0.$$

Without loss of generality, we can take  $K_1 = K_2 = 1$ . The associated loss functions are then called unit loss functions and results for the cases  $K_1 \neq 1$  can be deduced from these cases by multiplication by appropriate constants.

For a fixed  $\Theta$ ,  $\delta_\Theta(w_0)$  represents the average loss (also called risk) that results from taking  $w_0$  as the estimate of  $\Theta$ , using the  $L_1$  loss function. A similar conclusion holds for  $V_\Theta(w_0)$  and  $L_2$ .

**3.2.** The problem of building a normed linear space structure on a subset of probability distributions has not found a satisfactory answer yet. The dispersion measure  $\delta_2(\Theta)$  can provide a solution to that problem.

Let us consider the class of infinitely divisible distributions on  $\mathfrak{R}$  with the following operations on its independent members: convolution product  $F_1 * F_2$ , inverse function  $F^{-1}(a) = \inf\{x : F(x) > a\}$ , with  $Md(F) = F^{-1}(\frac{1}{2})$ , and degenerate distributions at any point are all identified to the neutral element.

**Theorem 1.** *Let  $\Xi$  be the class of infinitely divisible distributions. The  $\Xi$  is a closed normed linear space, with  $\|F\| = \delta_2(F)$ .*

*Proof.* We know that  $\Xi$  is closed under convolution and passage to the limit. Moreover, for independent  $X, F_1$  and  $F_2$  in  $\Xi$ , such that  $F_1 * X = F_2 * X$ , we have  $F_1 = F_2$ . Hence  $\Xi$  is a linear space. Moreover, defining the norm of  $F$  as above, we have  $\|F\| = 0$  iff  $F$  is degenerate. Also, for  $a \in \mathfrak{R}$ , we have  $\|aF\| = \delta_2(aX) = a\delta_2(X) = a\|F\|$  since  $\delta_2(X)$  is a measure of dispersion. Then

$$\|F_1 * F_2\| = \delta_2(X_1 + X_2) \leq \delta_2(X_1) + \delta_2(X_2) = \|F_1\| + \|F_2\|.$$

The first part of the double inequality

$$\delta_2(X_1) \leq \delta_2(X_1 + X_2) \leq \delta_2(X_1) + \delta_2(X_2)$$

is given by the dilation ordering (see [5]). For the second part, we note that

$$Pr(X + Y \leq Md(X) + Md(Y)) \geq Pr(X \leq Md(X)) + Pr(Y \leq Md(Y)).$$

Hence

$$Md(X + Y) \leq Md(X) + Md(Y)$$

and

$$E(|X + Y - Md(X + Y)|) \leq E(|X - Md(X)|) + E(|Y - Md(Y)|).$$

□

**3.3.** There are several possible constraints that could be imposed on an estimator in real applications and they could be of deterministic or stochastic types. In the following section we will consider the simple deterministic constraint that the value of the estimations is to be within a fixed interval  $[a, b]$ , with  $a < b$ .

**Theorem 2.** *Let  $\Theta$  be the parameter of interest in the statistical model  $\varphi(x|\theta)$  and let  $f(\theta)$  be its prior. If the estimation of  $\Theta$  must be in  $[a, b]$  then it can only take the value  $a$ , or  $b$ , or  $Md(\Theta)$ .*

*Proof.* Under the unit absolute value loss function, we have to consider the posterior distribution of  $\Theta$ , and find the value of the estimation that minimizes the posterior risk:  $\min_{w \in [a, b]} (\delta_\theta(w)) \geq \delta_2(\theta)$ . Hence, due to the convexity of the function  $\delta_\Theta(w)$ , which has a minimum at  $Md_{\text{post}}$ , with the corresponding posterior risk as  $\delta_{2, \text{post}}(\Theta)$  or, for the second case,  $b$  (if  $Md_{\text{post}} > b$ ), with as posterior risk  $\delta_{\Theta_{\text{post}}}(b)$ , or  $a$  ( $Md_{\text{post}} < a$ ), with as posterior risk  $\delta_{\Theta_{\text{post}}}(a)$ .

Let  $\Psi = \int_{\mathfrak{R}} f(\theta)h(x|\theta)d\theta$  be the predictive distribution of  $X$ . The Bayes risk is hence  $E_X(\delta_{\Theta_{\text{post}}}(\cdot))$ , with  $\cdot = a$  or  $b$ , or  $Md_{\text{post}}$ .

Similarly, for the quadratic loss function, we have  $\min_{w \in [a, b]} (V_\Theta(w)) \geq \sigma^2(\Theta)$ , where the convex function  $V_\Theta(w)$  attains its minimum  $\sigma^2(\Theta)$  at  $w = \mu_{\text{post}}$ . The

distributions of the corresponding errors  $U = |\Theta - w|$  and  $V = (\Theta - w)^2$ , for the estimated values determined above, have their means and variances given by

$$E(U) = \delta_{\Theta}(w), \quad Var(U) = \sigma_{\Theta}^2 - \delta_{\Theta}^2(w) + (\mu_{\Theta} - w)^2,$$

while

$$E(V) = \sigma_{\Theta}^2 - (\mu_{\Theta} - w)^2 \quad \text{and} \quad Var(V) = E[(\Theta - w)^4] + (\sigma_{\Theta}^2 + (\mu_{\Theta} - w)^2)^2,$$

with, in both cases,  $w = a$  or  $b$ , or  $\mu_{\text{post}}$ .  $\square$

**3.4.** For a constraint of stochastic type, we now consider the case when  $W$  itself could be a random variable with domain  $\Omega$ . In this case, we are often in presence of a family of random estimators  $\{W_j\}$ ,  $j = 1, 2, \dots, n$  and would like to identify the best distribution of the family. In the posterior distribution, the estimation of  $\Theta$  now follows the distribution of  $W$ , does not depend on the pointwise minimization of the posterior risk, but depends rather on the global minimization.

**Theorem 3.** *Let  $\{W_j\}$ ,  $j = 1, 2, \dots, n$  be a family of distributions of the estimator of  $\Theta$ . We have, for the absolute value loss function, the worst random decision distribution given by  $\max_{1 \leq j \leq n} \{\delta_{\Theta}(E(W_j))\}$ , and under the square-error loss function, by  $\max_{1 \leq j \leq n} \{V_{\Theta}(E(W_j))\}$ .*

*Proof.* As shown by Munoz-Perez and Sanchez-Gomez in [4],  $\delta_{\Theta}(w)$  is a convex function of  $w$ . Hence we have  $EW_j(\delta_{\Theta}(w_j)) \geq \delta_{\Theta}(E(W_j))$ , for  $j = j_0$  identifies  $W_{j_0}$  as the worst distribution. By step-to-step elimination, we can obtain the best distribution  $W^*$ .

Under the square error loss function, we have  $E_W(V_{\Theta}(w)) \geq V_{\Theta}(E(W))$ , and a similar conclusion is valid.

Thus, for the corresponding error variables  $U^* = |\Theta - W^*|$  and  $V^* = (\Theta - W^*)^2$  with  $\Theta^*$  and  $W^*$  being random variables, we have

$$E(U^*) = \iint_{\mathfrak{R}^2} |\theta - w| dF(w) dF(\theta),$$

$$Var(U^*) = \iint_{\mathfrak{R}^2} |\theta - w|^2 dF(w) dG(\theta) - [E(U^*)]^2$$

while

$$E(V^*) = \iint_{\mathfrak{R}^2} |\theta - w| dF(w) dG(\theta),$$

$$Var(V^*) = \iint_{\mathfrak{R}^2} |\theta - w|^4 dF(w) dG(\theta) - [E(V^*)]^2.$$

$\square$

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